# Jacobsen Declaration Exhibit D

Decoder Commander® Software

**KAM Industries** 

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## Decoder Commander<sup>®</sup> software

## Configuration and User Manual



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## **Overview of Train Server<sup>®</sup> Software**

KAM has been producing professional model railroad software since 1991 and is the leading supplier of Professional DCC software for the model railroad industry. All of KAM's software is scale independent, internet enabled, and supports all popular command stations.

Train Server is a software program (middleware) that handles the day to day management of the command station and coordinates the information flow between other Train Server applications. Train Server Architecture is a multi-user architecture that is unique in the model railroad industry in managing the model railroad communications interface. Most other DCC control applications are simple single user, single command station programs which do not allow information to be exchanged between simultaneously users on a real time basis.

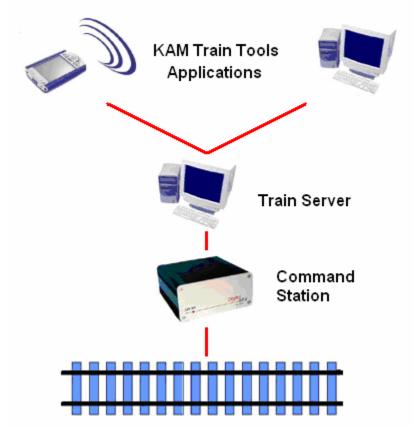


Figure 1: Train Server with Train Tools Applications

While the electrical signals sent through the layout to control DCC hardware is an industry standard, how application programs communicate to the command stations that generate these signals is vendor specific and often model specific. Train Server supports all popular command stations so that a single version of a DCC control application can be written that will work with all popular command stations now and into the future.

All KAM Train Tools applications communicate with Train Server in order to control the layout. When using a single PC, you can run these applications on the same PC as Train Server. (Microsoft's loopback driver must be installed if there is no network hardware installed. See website for details.) In a networked PC environment, only one PC needs to be running Train Server. Other computers running applications designed for use with Train Server can operate the layout remotely over the network through the "server" PC running Train Server.

#### **Train Server APIs**

KAM supports and encourages open application programming interfaces (APIs). We publish all interface information on our web site, as well as on our CD-ROMS.

Train Server software supports 3<sup>rd</sup> party vendor, end user, and KAM developed applications. While Train Server is designed to run on a Windows PC, it supports a well published, open programming interface using XML data over TCP/IP networks so applications may be developed for any operating system and programming language that supports TCP/IP networking. Train Server also supports an open Windows COM/ActiveX-based API for applications that run on the same computer as Train Server. In addition, network aware applications can easily be built with a KAM code library that greatly simplifies DCC application development in a Windows environment using any .NET programming language. For more information on interfacing your own applications to Train Server, please review the documentation shipped on your CD-ROM, or published on our web site.

#### **Decoder Commander and Programming**

KAM has two different programming philosophies for programming decoders, a simple programmer (Engine Commander<sup>®</sup> software) and a fully function do everything programmer (Decoder Commander).

Engine Commander implements a basic programming capability for programming decoders. Engine Commander allows you to read and write CV's, program decoder address and speed curve. There are no templates to determine what decoder model you are running, nor support for advance decoder programming or file operations. Engine commander programming is a simple programmer, allowing you to read and write your decoder.

Decoder Commander is a serious decoder programmer that allows you to do everything that Engine Commander does plus configure advance decoder functions, clone decoders, customize speed curves, configure advance function mapping and create customize decoder templates. Decoder Commander allows you full access to the manufacture specific decoder information so you may customize the decoder as you see fit.

## **Getting Started**

#### Installing Decoder Commander<sup>®</sup> Software

To install Decoder Commander insert the CD-ROM and follow the installation instructions supplied with your product. The default installation will only install a time limited demonstration version of the programs. To install licensed products, you will need to use your supplied serial number. This serial number is located on your CD-ROM or may be purchased on line from our web site. Your serial number will only install those applications that you have purchased. To install other demonstration applications you will need to use the custom installation option during your installation.

Applications designed to work with Train Server communicate only with Train Server to control the layout. For a single user, you can run these applications on the same PC as Train Server, but when multiple users would like to control the layout (or in the case of Loco CE you want to be able to control the layout wirelessly with a Pocket PC), only the PC with the command stations attached requires a running instance of Train Server.

If you wish to install only Decoder Commander on additional networked PCs, insert the CD-ROM and select the custom installation. Select Decoder Commander for installation and disable (uncheck) the other programs.

Train Server runs as a Windows process, not as an application with a user interface. Train Server Manager is an application used to start, stop, and configure Train Server.

## **Configuring Train Server**

Make sure your command station is connected to the PC that has Train Server installed and make sure the command station has power.

#### Start Train Server<sup>®</sup> Manager

The first time you run any Train Server application you need to configure the command stations you want to use.

• Run the Train Server Manger. It is located in your start menu in the "Train Tools" program group.

#### **Configure Command Stations**

• Click the "Interface Wizard" button in the Train Server Manager application. This wizard will guide you through configuring your command station. (See Figure 3)

Train	Server Interface	Manager			
Train Server® Interface version: [Program:2.4.030 Schema: 30, decoder 94]. US Patent 6065406, 6267061, 6270040, 6460567, 6494408, 6530329 Ger 29923834.2, GB2353228. One or more patents pending. Copyright 1991-2005, KAM Industries. All rights reserved					
Con	nected command statio	ons			
1.	Lenz:XpressNet(	OM1 🔽 On Reset 6.	Not Connected	🗖 On	
2.	Not Connected	🗌 🗌 On 🛛 7.	Not Connected	🗖 On	
3.	Not Connected	🗌 On 🛛 8.	Not Connected	🗖 On	
4.	Not Connected	🗌 🗌 On 🛛 🤧	Not Connected	🗖 On	
5.	Not Connected	🗌 On 🛛 10.	Not Connected	🗖 On	
Unloa	Inload Train Server Interface Wizard Objects In Use Hide Refresh				

Figure 2: Train Server Manager

• The first configuration setting is the "Logical Port". (See Figure 4) Generally a logical port refers to where the command station is plugged into the PC. (which serial port, such as COM1.) Logical ports are a useful way to organize these physical connections rather than the using the Windows-specific device names. Your computer might have a COM1 but the next port might be COM3. Or your command station might be connected through a USB port. Logical Ports allow multiple command stations to be configured with simple number assignments, regardless of their physical PC port connection. They also allow you to move a command station to a different physical port without needing to reconfigure any applications other than Train Server since the logical port will still refer to the same command station, even on a different physical port.

In most cases, the default values shown in the wizard will be fine. The most important configuration setting is the specific brand and model of command station connected. (See Figure 5) The remaining screens are set to the factory default values that ship with the command station selected.

Logical Interface Port		X
	You are about to configure one of the communications ports connected to your command station. Begin by choosing a logical port number to identify this port. Click Next to continue.	
	Logical Port	
< Bar	sk Next > Cancel Help	

Figure 3: Port selection screen

Select Command Station		×
	Choose the type of command station below. Click Next to continue.	
	Connect Status: Not Connected	
< Bac	Command Station Type: Lenz Express Net  Lenz Express Net Lenz Digital Plus KAM:NMRA Serial LenzLi-100	

Figure 4: Command station selection

RTS Flow Control     © Enable     BAUD Rate       C Disable     © Enable     19200       DTR Flow Control     © Disable     C Enable       C Disable     C Enable     Physical Port       C Handshake     C Common     COM1       X0N/X0FF (software)     COM1     X0N/X0FF (software)
--

Figure 5: Default serial port selection

Connect to Port		u are done conf sk Finish to conr	iguring a logical por nect to the port.	rt.
	0.0	Connect to this p Disconnect from Disconnect exist Finish		ctinew.port

Figure 6: Final selection screen

At this point you are ready to run any Train Server application. When Train Server manager is running, the program acts as a communications gateway for Train Server local and network applications.

Below are descriptions for additional features support by Train Server Manager. (See Figure 3)

- **Unload Train Server:** This is used to terminate Train Server from running on your computer. Train Server Manager will stop Train Server's processes (enginterface.exe and locoevents.exe). It will not stop any application using Train Server, so it is recommended you shut down all Train Server applications before unloading Train Server.
- **On**: This allows you to turn on the power to the layout (checked), or turn it off (unchecked).
- **Reset**: This is used to send a hardware reset to the command station. In some command stations this will purge the command station's current settings and restore the factory default values.
- **Refresh**: This is used to update the status of the connected command stations in Train Server Manager.
- *Hide*: Reduces Train Server Manager to an icon in the system tray.

## **Decoder Commander Basic Operations**

#### Start Train Server<sup>®</sup> Manager

If Train Server Manager is not yet running on the PC running Train Server, you must start Train Server Manager in order to start Train Server. If you have not yet configured any command stations, please read the previous section and complete this step first.

• Start Train Server Manger. It is located in your start menu in the "Train Tools" program group.

Train Server will remember the last command station configured, so you only need

to enter the command station information one time.

**TIP:** Train Server must be running before you continue. If you have not selected a command station in Train Server, Layout commander will not control the layout.

#### Start Decoder Commander®

• Start Decoder Commander. It is located in your start menu in the "Train Tools" program group.

When decoder commander starts for the first time, there is a delay while the software searches your disk for the latest templates. This may take a few minutes depending on the size of your disk.

Decoder Commander uses XML data templates that conform to the manufactures based decoder definition. See the section on templates later in this manual.

Select trainserver	
Select server Trainserver: 127.0.0.1 Network port: 1069	Connect
Cancel OK	

Figure 7: Decoder Commander main window

#### **Connect Decoder Commander to Train Server**

• Enter the TCP/IP address or the computer's network name that is running Train Server.

TCP/IP is the networking protocol used for Microsoft networks and the TCP/IP address is how each computer on the network is uniquely identified.

If your are running Decoder Commander on a different computer than the PC running Train Server you must enter the TCP/IP address or computer name of the PC running Train Server. See the Troubleshooting section of this manual for help in obtaining the TCP/IP address of another computer.

The first time Decoder Commander is run, it will use the TCP/IP address of the computer it is running on as the default value for the server address.

After Decoder Commander is run the first time, the default server address displayed will be the last address entered. Some networks use dynamically assigned TCP/IP addresses (DHCP) which can cause the address of a PC to change

when rebooted which will cause the previously used address to be incorrect. See the troubleshooting section for more information.

• Enter the TCP/IP port number that Train Server is using.

This will always be port 1069 unless Train Server was intentionally reconfigured.

• Click the "Connect" button.

#### **Decoder Commander Console**

Decoder Commander	
<u>Fi</u> le Trainserver <u>V</u> iew <u>L</u> anguage <u>H</u> elp	
Converte and the second of the	
Known decoders Decoder Commander using programming mode template	
▼ Programmer window   ● Report view   ● XML trace window   ● Trainserver message window	
KAM Initialisation	
Decoder tools	
Read from programmer track	
New from template	
Search decoder template	
Decoder templates Decoder test	
ady	NUM

Figure 8: Decoder Commander startup screen

After you have selected the connect button, Decoder Commander, connects to Train Server and loads any know decoder that you have programmed, and sets up the programming mode form your last session.

Decoder Commander uses decoder templates, that represents the manufactures model railroad decoders. These templates are used as input to create a new decoder that represents on of the locomotives on your layout.

You can create your own templates, but you will need to run those template samples through the KAM's template verification tool to build a template that will work with Decoder Commander. See "Templates" later in this manual.

#### Using Decoder Commander the first time

#### Terminology

Decoder Commander is a decoder programmer tool designed for programming model railroad decoders. Before you begin to program your model railroad decoders, there are a few terms that describe the operation of Decoder Commander and the capabilities of the software.

- Decoder A hardware component in your model train that controls the operation of the model train. Decoders have a control variable specification that defines the operations characteristic of the decoder and how the model train will operate.
- Control Variable Control Variables or CV's contain configuration information on the operation of the decoder. The CV's are defined by the National Model Railroad Organization (NMRA), and conform to a standard that all model train manufactures support.
- NMRA Standard The nmra Digital Computer Control(DCC) standard is located at <u>www.nmra.org</u>. The individual decoder specifications are located at <u>www.dcc.info</u>.
  - Manufactures who support the NMRA standard, display the NMRA conformance logo on their products.
- Programmer A software tool design to program the configuration variables on a mobile decoder. KAM's Decoder Commander is a software decoder programming tool.
- Templates All decoders have unique characteristics. KAM has created a set of Decoder Templates that has these characteristics in a XML configuration file.
- Template A tool supplied by KAM that will process a users template and Converter electronic build a decoder template that can be used by decoder commander. The template converter is described later in this manual.
- Command Station A hardware component used to control your model railroad layout. Command Stations support two different programming capabilities, Operation mode and service mode. Service mode requires a programming track for operation.
- Programming A command to change the CV in the decoder. Programming is either a "read" (service mode) or "write" (operations and service mode) for the desired CV.

Case 3:06-cv-01905-JSW	Document 115	Filed 10/25/2006	Page 13 of 37	
Decoder Commander <sup>®</sup> Software				
Read		be read in service mo		
			e programming mode	
Write		ritten in operations m te mode (on the prog	-	
	Decoder Commander unless the user over		e programming mode	
Operations mode		a programming mode erating on the layout		
	A decoder address ca mode.	an not be programme	ed in operations	
		y support an unverific because the decoder		
Decoder Address		an address that the otive on the model ra	•	
	locomotives have he	o not need to be unions and a same address and a solution of the second to any of the second	re on the layout, then	
Programming Track	A set of track attach program the decode	ed to a command sta r in service mode.	tion where you can	
Service Mode	programming track of there are three difference of the the three difference of	ogramming mode that on a command statior rent programming op n. These are page, dir	n. In service mode, erations support by	
		d to program the decomode uses different t a decoder.		
		ts both "read" and "v because the decoder		
Programming formats		rent types of progran r in service mode. T rect and register.		
		es use differ formats ming. This is the san		

decoders use different formats for programming as well.

Decoder Commander uses the decoder template programming value, and selects the correct programming mode for the decoder.

#### Programming a Decoder with the wizard

P Decoder Cor	nmander
$\sim$	(iew <u>L</u> anguage <u>H</u> elp
Known decoders	Decoder Commander using programming mode: te
	🌋 Programmer window 🛛 🖲 Report view 🕒 XML trace window 🏼 🖉 T
	KAM Initialisation
	Decoder tools
	Bead from programmer track
	New from template
	Search decoder template

Figure 9: Programming your first decoder

Figure 10: Automatic Train control on a large layout

• Decoder Commander uses programming wizard when you program a decoder for the first time.

**TIP:** Before you start the decoder template wizard, create a directory called "My Decoders". Locate this directory in the "My Documents" directory. This will allow you to save your decoders to disk.

Decoder Commander uses both the NMRA service mode programming and the operations mode programming.

When you program a locomotive decoder for the first time, you will need to place the locomotive decoder on the service mode programming track to program the decoder CV's. After the decoder is programmed, you can program the decoder on the mainline.

 Select either the "new" file or "new from template" to begin the programming process for your locomotive decoder.

Create decode	r project 🛛 🗙
	Create decoder entry         This wizzard creates the database entry for the selected decoder temolate         Public Domain _Do-It-Yourself Decoders (I         Public Domain _Do-It-Yourself Decoders (I         Model Rectifier Corp. (MRC)         Unknown         NCE Corporation(formerly North Coast Enc         QS Industries (QSI)         Bit AC5 Cab Forward 4-8-8-2-         Atlas B23-7 - QSI Diesel         BIT AC5 Cab Forward 4-8-8-2-         Atlas B23-7 - QSI Diesel         BIT AC5 Cab Forward 4-8-8-2-         Atlas B23-7 - QSI Diesel         BIT AC5 Cab Forward 4-8-8-2-         Atlas B23-7 - QSI Diesel         BIT AC5 Cab Forward 4-8-8-2-         Atlas B23-7 - QSI Diesel         BIT AC5 Cab Forward 4-8-8-2-         Atlas B23-7 - QSI Diesel         BIT AC5 Cab Forward 4-8-8-2-         Atlas B23-7 - QSI Diesel         BIT AC5 - QSI Electric         BL GG-1 - QSI Electric         BL GG-1 - QSI Electric         Decoder templates         Selected templates

Figure 11: Running Decoder Commander Programming wizard

After starting the wizard, select the decoder template that matches your decoder ٠ as close as possible. In our example, we have selected an QSI decoder from Baltimore Limited.

All of the information collected from the decoder will be stored in a readable data file. You can use the Decoder Commander to print out the decoder information, or any other third party tool that can read the Decoder Commander data format.

Select next and enter information about the decoder project

Create decoder	project	X
	New from template Define the loco parameters Template: BLI GG-1 - QSI Electric Projectmame: Pennsy GG 27 Addressing: Short adddress 27 Long address 0	
	<pre></pre>	sh

Figure 12: Entering project information for your decoder

**TIP:** When you name a decoder project, name it with a value that is descriptive of the locomotive. This will make it easier to maintain the decoder over time.

- Select next after you have entered the decoder address and project name
- Select a directory where you would like to save the decoder information that you have created. You can save this information anywhere on your disk. Create a directory in My Documents called "My Decoders".

Create decoder p	roject	×					
	Create Decoder Entry						
	This step prepares the database entry						
	Template: BLI GG-1 - QSI Electric Decoder name: Pennsy GG 27 Addressing: 27 / 0						
	Select folder	~					
	My Documents\inventory filnal\Inventory\Pocket Inventory My Documents\inventory filnal\Inventory\Pocket Inventory My Documents\inventory filnal\Inventory\Pocket Inventory My Documents\My Archives My Documents\My Achives My Documents\My Books My Documents\My Pictures My Documents\My Pictures My Documents\My Pictures My Documents\My Videos My Documents\My Videos My Documents\Ulead VideoStudio	*					
	 kack next> cancel finis	h					

Figure 13: Entering project information for your decoder

• The Programming wizard allows you to specify the programming operation that you want to perform on the decoder.

There are three programming models that you can perform at this step, you can create a new template from the master templates (no programming), you can clone a template from a previous locomotive, or not program anything and create your own template file for later modification. These options are described in the table below.

- Clone decoder (optional) Select the decoder that you wish to copy. This will read one of your existing decoders, and either program the decoder, or create a new template file for use with the wizard
- Create a template (optional) If this option is selected, a new template file will be created to use with Decoder Commanders template wizard. This is useful to create a decoder file that you can modify. If you modify a template file, you will need to run the template verification tool on your file.

- Read a decoder Read a decoder's CV's form the programming track and save the information to your decoder database for this locomotive
- Write a decoder Write a decoders CV's to the programming track from the template file or a clone decoder (if selected).

It is best to clone a decoder on write operations, unless your club layout has a decoder standard, then you will use that decoder template.

**TIP:** When programming a new locomotive, place the locomotive on the programming track, before you decoder commander wizard. If you have purchased a sound decoder, check the manufactures instructions on programming. You may need to purchase a programming booster to program this decoder.

Create decoder project 🛛 🗙							
	Create decoder entry         Define the loco parameters         Template:       BLI GG-1 - QSI Electric         Decoder name:       Pennsy GG 27         Clone decoder:           Select Operation:           Create template           Read decoder and save values to template         Write decoder values from template         Program       Abort operation						

Figure 14: Entering project information for your decoder

Figure 14, shows that have decided to "read the decoder", and store the information into our decoder file, under the name of "Pennsy GG 27". To start the operation, we select program.

**TIP:** reading and writing a decoder takes time.. The read/write time may be upwards of 30 seconds per CV. Advance decoders typically have 50 CV's, so it is not uncommon to wait 10 minuets to read or write a mobile decoder.

• To begin the programming operation, select "Program". If you wish to abort the programming cycle, select "Abort". Stopping a command station programming sequence may take 30 seconds or more to stop the programming cycle.

Create decoder project 🛛 🔀							
	Create decoder entry						
EFFAL.	Define the loco parameters Template: BLI GG-1 - QSI Electric						
2000 MM	Decoder name: Penssy GG 27						
	Clone decoder:	*					
	Select Operation: Create template Read decoder and save values to template						
	Write decoder values from template 38 of 43 processed, result cv=95, val=128						
	Program Abort operation						
	<pre></pre>						

Figure 15: Programming operation status update

• At the end of the programming cycle, you select finish. This will update the Decoder in your known decoder list.

Figure 15, shows the status update of the programming operation. This display will show you the number of CV's that are processed, and the value of each CV.

P Decoder Commander Penssy GG 27								
File Trainserver View Langu								
Known decoders	Decoder Commander using programming mode: templat							
Penssy GG 27	Programmer window Report view SXML trace window P Trainser Address settings							
	Decoder tools         CC Primary Address           Image: Short address         27           Address settings         27							
	CLong address							

Figure 16: Status area updated with new Decoder information

After you have completed the programming operation, the Decoder Commander console is updated with the decoder information that we just read earlier.

Decoder Commander will scan your hard drive when Decoder Commander is started. The decoder information is stored in a XML data file in the directory that you specified.

new decoder information. decoder tha tFigure 15, shows the status update of the programming operation. This display will show you the number of CV's that are processed, and the value of each CV.

## **Configuration Options and Tools**

#### **Decoder Tools**

Known decoders	Decoder Commander using programming mode: template
Pennsy 00 27	Programmer window & Report view O XML trace window O Trainserver message window
	Address settings
	Decoder tools     DCC Primary Address       Address settings     Image: Short address       Address settings     Image: Short address       Image: Decoder tools     Image: Decoder tools       Image: Decoder tools     Image: Decoder tool
	Driving attributes  CV19: Consist Address  CV19: Consist activ  Current value:  Current value: Current value:
	FX Options     CV21: Consist Address Active For F1       Image: Function matrix     Image: Consist Address Active For F1       Function matrix     Image: Consist Address Active For F1       Image: Consist Address Active For F1     Image: Consist Address Active For F1       Image: Consist Address Active For F1     Image: Consist Address Active For F1       Image: Consist Address Active For F1     Image: Consist Address Active For F1       Image: Consist Address Active For F1     Image: Consist Address Active For F1
	Variable overview       CV22: Consist Address Active For FL in Forward         Image: Consist activ       Image: Consist activ         Define single variable       Current value:
C Decoder templates	Decoder test

Figure 17: Programming with Decoder Commander Tools

You can use "Decoder Tools" to program your decoder. Decoder Tools allows you to program individual CV's, as groups of CV's. To use the Decoder Tools, select one of the known decoders (such as the "Pennsy GG 27"). Known decoders are decoder's whose data files are located on your disk. Known decoders are created using Decoder Commander programming wizard.

In figure 16, we have selected our decoder "Pennsy GG 27" to use. The Decoder Tools menu expands with the decoder tool options. In our example, we have started a programming operation (read was selected). The values that will be read, are changed to -1, and are colored red. Once the decoder values are returned from the command station these values are updated to returned values, and the background changes to white.

-CV19: Consist Address
Consist activ
Current value: 12
Consist Direction Reversed
- CV21: Cons <mark>ist Address Active F</mark> or F1
☑ Consis <mark>t</mark> activ
Current value: 2710
Consist Address Active For F8 Respond to
-CV22: Consist Address Active For FL in Forward
Consist activ
Current value: 3

Figure 18: Information display on programming CV's

Decoder Commander allows you to program individual CV's in a group, and displays the status information about the programming operation. Decoder Commander uses KAM's Smart Decoder Technology to determine which CV needs to be written and updated to the decoder.

Yellow Shows a changed value for write operations. This value will be written to the decoder when the user depress the write operation.

Values that are in white are ignore on decoder write operation.

Red If the number displayed is in red and is not a -1, then this value is an error value. The value entered is out of range for the CV.

A -1 value in red, means that this information is being read from the decoder. The return value will be updated as clear text

**TIP:** If you wish to abort a programming operation, just select a different "decoder Tool". This action will abort the programming operation.

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Decoder Commander<sup>®</sup> Software

#### **Address Setting**

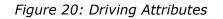
Decodertools	DCC Primary Address     Short address     Long address	Manufacturer default
Driving attributes	CV19: Consist Address	
Analog function	Current value: 0 Consist Direction Reversed	Manufacturer default
FX Options	CV21: Consist Address Active For F1	
Function matrix	Consist activ Current value: 12 Consist Address Active For F8 Respond to	Manufacturer default
l fû	CV22: Consist Address Active For FL in Forward	
Variable overview	Consist activ Current value:	Manufacturer default
	Requested Operation: Read Write	
Decoder test		

Figure 19: Address setting CV's

Decoder addresses can only be program in service mode, and not in operations mode, with the exception of consist packet information (CV21 and CV22). All other CV's can be programmed on the main.

#### **Driving Attributes**

Decoder tools		
Address settings	CV29: Decoder configuration  14 Speed Steps  28 / 128 Speed Steps	
Priving attributes	CV29: Reverse driving	
and the second sec	✓ Locomotive Direction reversed	
Analog function	CV29: Decoder configuration	
and the second s	Speed Table Definition Use QSI table or User table in CVs 67 through 94	
FX Options	CV29: Decoder configuration	
ê0∎	Address Format Two byte (extended) address	
Function matrix	Requested Operation:	
Variable overview	Read Write	
•		
Define single variable		
Decoder test		



Driving attributes are those CV's that effect the operation characteristics of the locomotive decoder. Driving characteristics include speed step (14/28 mode), enabling a decoder speed table by use of the decoder, and to set the locomotives direction of operation (used for double headers)

#### Analog Functions

Decoder tools	CV29: Activate analog function
Address settings	Power Source Conversion DC conversion enabled
Driving attributes	Requested Operation:
alog function	
FX Options	
Function matrix	
Variable overview	
Define single variable	
Decoder test	

Figure 21: Analog Functions

Analog function support allows the locomotive to operate in analog mode, on a model railroad layout where a Digital Command and Control systems is not available. This capability is unique to each decoder, and is not universal across all decoders that are produced. If you wich to run your locomotive on a layout that does not support DCC, you will need to have CV29 analog mode enabled.

**TIP:** Analog mode does not always work with all Locomotives motors. You will need to check with the locomotive manufacturer to verify if the locomotive motor supports analog operation.

Likewise, all locomotive motors do not support DCC. Iron core motor typically will heat up and burn out on DCC layouts unless there is some electrical modifications made to the motor circuit.

#### **FX Options**

Decoder tools	CV25: Quantum Speed Table
Address settings	Current value: 0 User Defined Speed Table Manufacturer default
Driving attributes	CV53: Outout 10 - Forward/Reverse Only
and the second s	Current value: 0 Dynamic Brakes Manufacturer default
Analog function	CV53: - Neutral Only Short Air Let-off Mute
FX Options	Current value:         D         Doppler Shift Headlight         Manufacturer default           Dim Headlight         Manufacturer default         Manufacturer default
Speed curve	Reverse Light           Automatic Cab Lights           Directional Mars Light
Function matrix	Current value:  Mars Light Strobe Mars Light Number Board Lights Directional Headlight + Directional Mars Light
۹0	CV53: - Neutral Only Directional Direction
Variable overview 승규노	Current value: 0 Stobe Ditch Lights Cruise Control Scale mph Report and Status Report
للالع) Define single variable	Coupler Effect CV53: - Neutral Only Squealing Brakes Squealing Brakes + Air Brakes
	Current value: 0 Dynamic Brakes Manufacturer default

Figure 22: FX Function support

FX function support allows you to define the function bit modes of the decoder. These modes allow you different operating characteristics of the locomotive on the layout. Check with your decoder manufacturer to verify that bit mode is supported

#### **Speed Curve**

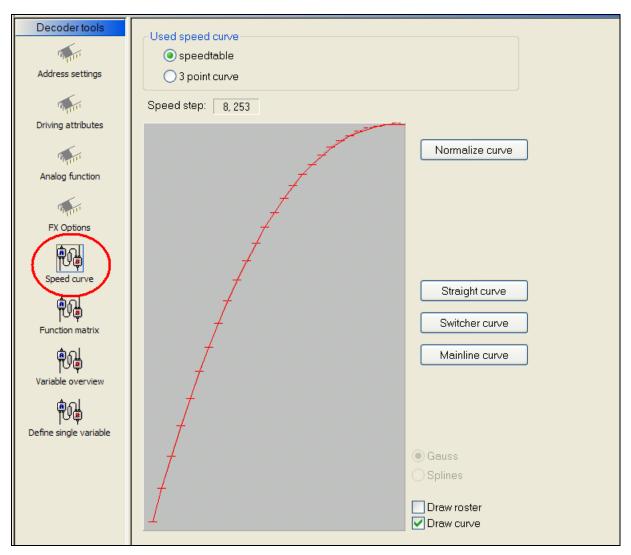


Figure 23: Speed Curve support

Decoder Commander supports speed, if the locomotive decoder supports speed curve. The decoder tools allows you to define any type of speed curve that makes sense for you locomotive. The tools support some preprogrammed speed curves, that would represent a switcher and mainline (freight/passenger).

On any speed curve, you need to be able to modify the speed curve. The decoder Tools, allow you to modify individual elements and normalized the curve.

If you choose a "read" operation, the decoder will be read, and the speed curve will updated based on the information from the locomotive.

**TIP:** Before you modify a speed curve, always read the speed curve from the locomotive. This will give you a base line to make your speed curve modifications.

#### **Function Matrix**

Decoder tools		Fwd light	Re∨ light	F1	F2	F3	F4	F5	F6	F7	F8	F9	E10	F11	E12	 
Sec.	Fwd light	~	Reviign								го	1.2	FIU	FII	F12	
Address settings	Re∨light F1		<b>v</b>	Ē												
and the second sec	F2 F3	7	<b>V</b>	7	<b>V</b>											
Driving attributes	F4 F5				<b>&gt;</b>											
The second s	F6 F7															
Analog function	F8 F9														Г	
ann.	F10 F11															
FX Options	F12							Γ	Γ	Γ	Π	Π	Γ	Γ	Γ	
₽ ₽ ₽																
Speed curve																
Function matrix																
Variable overview																
Define single variable	Manufactur Value:	er Konfigurat	on		Me	nufact	urer d	efault								
								- Audit								
	Operation F	Requested:-														
								Read			V	/rite				

Figure 24: Function Matrix mapping

Some decoders allow you to cross map the decoder functions, this is useful if you want to have a different operation sequence. For example, if you may desire to configure ditch lights of the locomotive when the head light is turned on. Another example, would be the operation of an uncoupler in a switcher. In running a switcher, you may desire to map the uncoupler to the rev light, so when a switch changes direction you can dropt he cars behind it..

In both of theses cases, you would map the decoder functions in the function matrix as shown above.

#### Variable Overview

Decoder tools	CV1: Primary Address	
Address settings	Current value: 27	Manufacturer default
Driving attributes	CV2: Vstart	
Analog function	Current value: 32	Manufacturer default
FX Options	CV3: Acceleration Rate	
Speed curve	Current value: 3	Manufacturer default
Function matrix	CV4: Deceleration Rate	
	Current value: 3	Manufacturer default
Priable overview	CV5: Max Volts	
Define single variable	Current value: 1	Manufacturer default

Figure 25: Decoder CV Overview

Variable Overview allows you to read and write a single CV variable or multiple CV variables to the decoder. The CV values and descriptions are from the decoder template. The CV's are programmed based on the template that is used, or Decoder Commander programming override.

To program a CV, find the correct CV that you wish to program, and move the slider till the appropriate value. Change one or all values. When it is time to program, Decoder Commander will program the CV's to the desired state.

Select the desired programming operation, either read or write. You can view the programming status in the status bar or the message window.

Decoder tools	Quantum Speed Table       Method         Image: Bit 1       Paging         Image: Bit 2       Paging         Image: Bit 3       Direct         Image: Bit 5       Bit 6         Image: Bit 7       Bit 8         Image: Bit 8       Example 1
Speed curve Function matrix Variable overview Define single variable	Read Write

#### **Define Single Variable**

Figure 26: Single CV variable programming

Define single variable allows you to read and write a single CV variable to the decoder. The decoder template contains the necessary information about the decoder's CV, and displays that information. The programming operations displayed are derived from the decoder template.

#### **Programming Information Windows**

#### **Status Menus**

Decoder Commander maintains a runtime control of the decoder operations. There are four different status menus, Programmer window (default), report view, XML trace window and Train server message window.

#### **Programmer window**

The programmer window is the default view that allows the user to control the programming operations in decoder commander.

#### **Report view window**

The report view window is a print view of the decoder characteristics. This view is updated real time when the changes are reported by train server. If you desired to print a decoder summary, display the report view first, then select he print operation from the file menu.

🌋 Programmer w	indow 🏾 🤨 Report vi	iew 🔉 XML trace window 🖉 🕫 Trainserver message window
<< <	> >>	
Summary	for decoder: Penns	y GG 27
Manufacturer:	QS Industries (QSI)	
cv	Value	Name
1	27	Primary Address
2	32	Vstart
3	3	Acceleration Rate
4	3	Deceleration Rate
5	1	Max Volts
7	5	Manufacturer Version No
8	113	Manufacturer ID

Figure 27: Report View print window

#### **Train Server Message Window**

🗯 Pr	ogrammer window 🔹 Report view 오 XML trace window 🖉 Trainserver message window
Port	Message
1	Program: Direct mode
1	Program: Writing cv 29
1	Program: Complete
1	Program: Direct mode
1	Program: Writing cv 29
1	Program: Complete
1	Program: Direct mode
1	Program: Writing cv 29
1	Program: Complete

Figure 28: Train Server status window

Train Server message window displays the message feedback information from the command station.

Decoder Commander Template

#### **Creating a Template**

Decoder Commander uses a set of smart tags for template formats. These smart tags control new features displayed in Decoder Commander Console. You can create new template files of you own

**TIP:** If you wish to create a new template, always store the template in a directory other then the installed directory. This way your custom templates will not be overwritten by a software update.

Creating a new template is simple, follow these steps

- 1. Run the Decoder Programming wizard
- 2. Enter a Template name, and a directory to store it
- 3. Enter address "3" to as an address for the template
- 4. Select "Create Template" option in the last step of the wizard

Your new template will be created in the directory that you specified. You can now modify this template, and make changes. When you are completed with the changes in your template, you need to perform two steps.

- 1. Load the template file into Internet explorer and verifiy that your XMI data format is correct
- 2. Run the Template verification tool to verify the template data and to make sure the template is compatible with Decoder Commander.
- 3. Start up Decoder Commander and begin to use your new template to program your decoders.

Testing your template is extremely important. The most minor change, can break your template. Always test any change that you make with the above three steps. The final step is to run the template through the Template verification tool. This tool will make sure that your template is valid for use with decoder Commander.

**TIP:** Detailed information about the decoder configuration variables may be found on the http://www.nmra.org web site, and the technical group website at http://www.dcc.info. Please refer to these web site for the latest information about the NMRA standard for Digital Command Control (DCC) advance attributes, Control Variables (CV's). Decoder Commander uses the NMRA standard when ever possible for decoder information and characteristics.

#### **Template Verification Tool**

The Template Verification Tool is a tool that KAM has released to allow you to create your own template file, and use third party templates, and convert them into a format that is useable by Decoder Commander. The Template Verification Tool properly configures the XML syntax, and adds the missing syntax information that is required to use the various "Decoder Tools" in Decoder Commander..

#### Using the verification Tool

TBD

#### **Template Format**

#### **Template Elements**

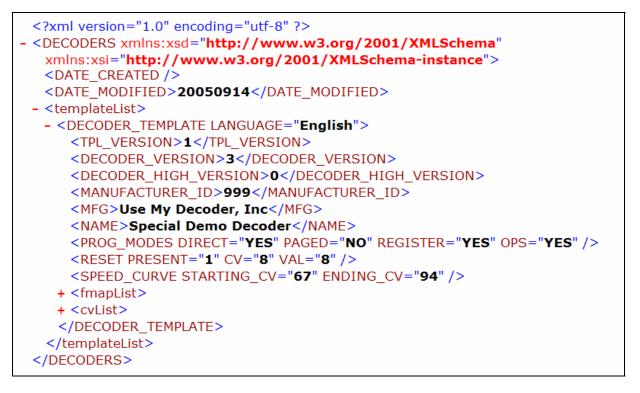


Figure 29: Template List parameter on Decoder Commanders XML Template file

#### **Template Capabilities (templateList)**

The <templatelist> describes the primary features of the decoder template file. These features are described in the table below

DECODER_TEMPLATE	This is the language of the template. All text
LANGUAGE	descriptions will conform to the template language.

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C	Decoder Commander <sup>®</sup> Software
TPL_VERSION	When a modification is made to the template file, the template version number should change to the new version number.
DECODER_VERSION	Manufacturer version number that this template file corresponds to. When the manufacturer released the template file.
DECODER_HIGH_VERSION	Extended manufacturer version information about the decoder
MANUFACTURE_ID	The NMRA manufacturer ID
MFG	The NMRA manufacturer's name that corresponds to the Manufacturer ID
NAME	The descriptive marketing name of the decoder
PROG_MODES	Programming modes that the decoder can support. This is different the command stations programming support. The common subset is the programming mode that is used by Train Server to program the decoder.
RESET PRESENT	New decoders have the capability to be reset to the Manufacturers default value. This is the reset value and CV that is used to reset the decoder to the Manufacture default state.
SPEED_CURVE	Most decoders support a speed curve. This element describes the starting and stopping CV range of the speed curve. If this value is not present, then the sped curve will not be displayed.
	The decoder speed characteristics are displayed in the <i>Decoder Tools</i> "Speed curve"
fmlist	Some decoders support function mapping. This parameter enables the function mapping of the decoder. This capability is not present in all decoders.
	The decoder function matrix is displayed in the <i>Decoder</i> <i>Tools</i> "Function Matrix"
cvlist	This a listing of the CV values and description.
	The decoder CV characteristics are displayed in the Decoder Tools "Variable Overview"

#### Function Mapping (*fmlist*)

Function mapping list is the mapping (*fmlist*) of the decoder functions or the function matrix. These function attributes are located in the "Decoder Tools", function matrix. The function mapping contains 4 values that describes how the function is mapped as it conforms to the NMRA DCC specifications.

- <fmaplist></fmaplist>
<fmap cv="33" defval="1" fname="Fwd light" mask="255"></fmap>
<fmap cv="34" defval="2" fname="Rev light" mask="255"></fmap>
<fmap cv="35" defval="4" fname="F1" mask="255"></fmap>
<fmap cv="36" defval="8" fname="F2" mask="255"></fmap>
<fmap cv="37" defval="16" fname="F3" mask="2040"></fmap>
<fmap cv="38" defval="32" fname="F4" mask="2040"></fmap>
<fmap cv="39" defval="64" fname="F5" mask="2040"></fmap>
<fmap cv="40" defval="128" fname="F6" mask="2040"></fmap>
<fmap cv="41" defval="256" fname="F7" mask="2040"></fmap>
<fmap cv="42" defval="512" fname="F8" mask="2040"></fmap>
<fmap cv="43" defval="1024" fname="F9" mask="16320"></fmap>
<fmap cv="44" defval="2048" fname="F10" mask="16320"></fmap>

Figure 30: Function Mapping parameter on Decoder Commanders XML Template file

CV	The CV number for the function mapping
DEFVAL	The default value for the function mapping
MASK	The mask used for the function mapping. The mask is used to define how granular the function mapping is. On earlier decoder, the function mapping was only a few bits. 255 is an 8 bit function mask.
FNAME	The function mapped name

#### CV Definitions (cvlist)

The cvlist contains the CV definitions that Decoder Commander uses to program the decoder. This information is displayed in the "Decoder Tools" menu, as "Variable Overview" and "Define Single Variable"

The cvlist data format corresponds to the NMRA organization definition for control variables. However, the NMRA has only defined a limited number of CV variables. There are a large number of CV variables that are available for users to use. Decoder Commander is designed to be extended by the user and to display these variables in the Decoder Commander Console.

```
- <CV INDEX="29">
   <DEFAULT>3</DEFAULT>
   <MIN>O</MIN>
   <MAX>255</MAX>
   <NAME>Normal direction of motion</NAME>
   <BITS BITS_DEFINED="YES" />
 - <BIT DEFINITION>
    <BIT_0>Normal direction of motion reverse</BIT_0>
    <BIT 1>Speed steps 28 speed step format</BIT 1>
    <BIT_2>Analog (DC) Operation DC conversion enabled</BIT_2>
    <BIT_3 />
    <BIT_4 />
    <BIT_5>Address Format Two byte (extended) address</BIT_5>
    <BIT_6 />
    <BIT_7 />
   </BIT_DEFINITION>
   <DATE_MODIFIED />
   <BitMask>0000001</BitMask>
   <stringList />
  </CV>
```

Figure 31: CV list parameter on Decoder Commanders XML Template file

CV INDEX	The CV number that that CV corresponds to.
DEFAULT	Default value of the CV
MIN	The minimum value of the CV
ΜΑΧ	The max value of the CV
NAME	The descriptive name of the CV. This descriptive name should be in the language of the template.
BITS BITS_DEFINED	This identifies if the bit position in the CV have a unique format.
BIT_0 BIT_7	If the BITS_DEFINED value is yes, then these are the corresponding bits for the CV register. Each value contains a description of the bit. This description is in the language of the template.
DATE_MODIFIED	An text string that used for modification information for the CV template.
BitMask	The bit mask used to define the bit parameters.
stringlist	A list of strings that corresponds to different values of the CV contents. For example, a value of 1, would correspond to the first element, a value of 2 would correspond to the second element.

The stringlist is used when the BITS\_DEFINED is set to "NO". and example of the parameter could be the following <BitName>Dynamic Brakes</BitName>

### Troubleshooting

#### How To Obtain The TCP/IP Address Of A Computer

- From the Windows Start Menu, select "Run..."
- Enter "cmd" (no quotes) and click the OK button.
- In the command window that opens, type "IPCONFIG" (no quotes) and hit the enter key on the keyboard.
- The IP address of this computer will be displayed. Use this value for the server address in Decoder Commander.

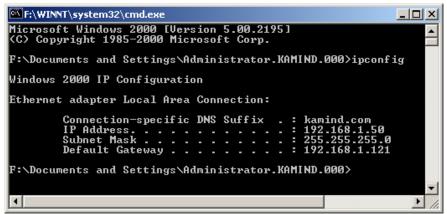


Figure 32: Running IPCONFIG to determine the TCP/IP address

#### **Cannot Connect To Train Server**

- This is most commonly caused because Train Server has not been started using Train Server Manager.
- If Train Server is running on another computer, you must enter that server's name or TCP/IP address, not the name or address of the computer running Decoder Commander.
- The TCP/IP address of the PC running Train Server may be incorrect.

Most networks use dynamic TCP/IP address assignments (DHCP). This can cause TCP/IP addresses to change each time a computer is rebooted. The easiest way to prevent addresses from changing is to configure the router to "lease" TCP/IP addresses for a longer period of time. With TCP/IP address leasing, a computer gets to keep the previously used address as long as it logs in again within the expiration period of the lease (usually measured in days).

Another way to prevent addresses from changing is to manually assign static TCP/IP addresses and either not use DHCP or assign these static addresses outside

of the range of addresses DHCP manages. Use IPCONFIG (described above) to determine the assigned TCP/IP address of a PC.

You can also use the name of the computer running Train Server. Even if DHCP assigns a new TCP/IP address to the computer, the computer name won't change unexpectedly when it reboots. A computer's name is easier to remember than its TCP/IP address but on some networks looking up a computer by name can be less reliable than using its TCP/IP address. Sometimes it may become necessary to help the name lookups by adding another computer's name and TCP/IP address into a computer's LMHOST file. The LMHOST file is located in the "/Windows/System32/drivers/etc/" folder. Of course, since the TCP/IP address of each computer must be typed into the LMHOST file, the lookup will fail if a computer's TCP/IP address.

• TCP/IP port 1069 communication may be blocked.

Train Server listens for connections on TCP/IP port number 1069. Firewall programs (such as Windows Firewall with XP) could be blocking that port from being able to communicate over the network. All computers running Engine Command and the computer running Train Server must have this TCP/IP port unblocked.

To unblock TCP/IP port 1069 in Windows Firewall, follow these steps: (For other firewalls refer to the manufacturer's documentation.)

- Open the Windows Control Panel. (Start menu -> Control Panel)
- Double click on Windows Firewall.

To verify if Windows Firewall is the problem you can temporarily disable Windows Firewall protection by clicking the "Off" radio button and then the OK button. Next try to connect Decoder Commander to Train Server. *Be sure to reactivate Windows Firewall afterwards to protect your computer!* If this solves the problem, turn Windows Firewall back on and continue these steps to unblock port 1069.

- Click the Advanced tab.
- Select your Local Areas Connection and then click the "Settings..." button.
- In the "Services" tab, if there is not already an entry for "tcp 1069" click the "Add..." button. Then enter either this computer's name or TCP/IP address, 1069 for the external and internal ports, and make sure TCP is selected. Then click the OK button.

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Decoder Commander<sup>®</sup> Software

Service Settings ?X
Description of service:
tcp 1069
<u>Name or IP address (for example 192.168.0.12) of the computer hosting this service on your network:</u>
192.168.1.8
External Port number for this service:
1069 O <u>I</u> CP <u>U</u> DP
Internal Port number for this service:
1069
OK Cancel

Figure 33: Unblocking TCP/IP Port 1069